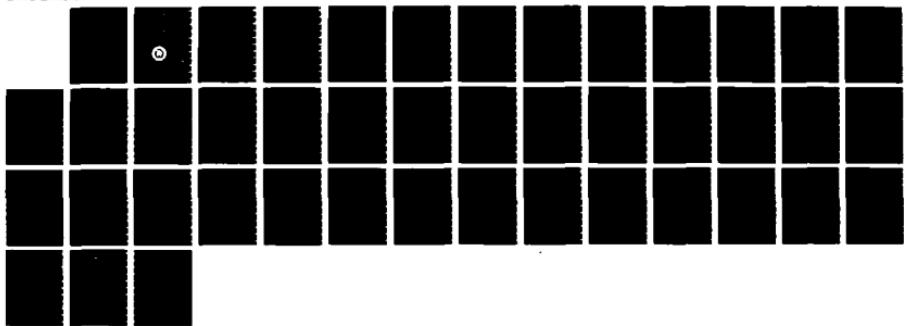
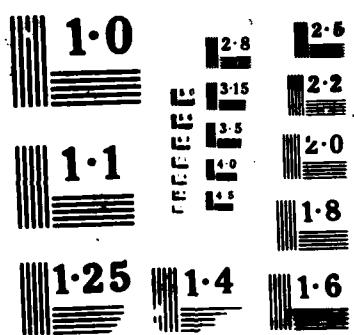


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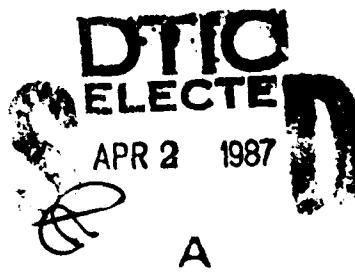
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**AN ALGORITHM FOR THE COMPUTATION OF GENERALIZED
LIKELIHOOD OR SELF-CRITICAL ESTIMATORS
FOR BINARY DATA**

by

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An Algorithm for the Computation of Generalized Likelihood
or Self-Critical Estimators for Binary Data

by

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and

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Rensselaer Polytechnic Institute



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Documentation for Self-Critical Binary Program

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1. Purpose

Subroutine BINARY is an implementation of the self-critical estimation procedure of Paulson, Presser and Lawrence (1983). The logistic, Gaussian or Type I extreme value distribution may be selected as tolerance distribution. Estimates are expressed in location-scale form on entry and exit, but results may be printed out in regression form, location-scale form, or in both forms (see Section 3 for a description of the two parametrizations). It is possible to hold location parameters constant during the estimation procedure. Estimation is accomplished by a Newton-Raphson method.

2. Specification (FORTRAN)

SUBROUTINE BINARY (N, IX, X, IA, NPAR, ISUB, ISTART, IDEP, IDIST, C,
RELTOL, ABSTOL, MAXIT, IPRINT, IFLAG, BETA, XLOGL, ICOV, COV, LMEM,
MEMORY, IPFAULT)

3. Description

The routine is applicable to the following modeling situation: For $i = 1, \dots, n$ (n is the sample size), let v_i be the stress variable, a_i a zero-one indicator of withstand or failure, and $X_i = (x_{i1}, \dots, x_{ip})^T$ a column vector of covariates. A constant is incorporated as a covariate identically equal to unity. The case $p=0$ is possible, but should be rare.

The tolerance distribution and density, $P(v_i)$ and $f(v_i)$ respectively, depend on the covariates, a scale parameter σ , and a vector of location parameters $\beta = (\beta_1, \dots, \beta_p)^T$ as follows, where

$$u_1 = \frac{(v_1 - \beta' x_1)}{\sigma},$$

- logistic, $P(v_1) = \frac{\exp(u_1)}{1+\exp(u_1)},$

$$f(v_1) = \frac{1}{|\sigma|} \frac{\exp(u_1)}{(1+\exp(u_1))^2};$$

- Gaussian, $P(v_1) = \Phi(u_1)$

(Φ is the standard Normal distribution function),

$$f(v_1) = \frac{1}{|\sigma| \sqrt{2\pi}} \exp(-\frac{1}{2} u_1^2);$$

- extreme value, $P(v_1) = 1 - \exp(-\exp(u_1)),$

$$f(v_1) = \frac{1}{|\sigma|} \exp(u_1 - \exp(u_1)).$$

In principle, it is possible for σ to be negative, but this contradicts the physical notion of a stress variable.

In the method of maximum likelihood, parameters θ are estimated by maximizing the log likelihood,

$$L(\theta) = \sum_{i=1}^n [a_i \log P(v_i) + (1-a_i) \log S(v_i)],$$

where $S = 1-P$. The self-critical procedure depends on a user-specified quantity c , and estimates θ by solving the system

$$\sum_{i=1}^n f^c(v_i) \left[a_i \frac{\partial}{\partial \theta} \log P(v_i) + (1-a_i) \frac{\partial}{\partial \theta} \log S(v_i) \right] = 0.$$

When $c = 0$, maximum likelihood estimates are obtained. As c increases from zero, increasingly robust estimators result. The sensitivity of parameter estimates to departures from model assumptions can be examined by starting with $c = 0$ and refitting the model for increasing values of c . Negative values of c seem less useful.

6. Numerical Method

For the purpose of estimation, the routine (internally) reparameterizes the problem in a "regression" form. In this parameterization, $F(\cdot)$ depends on

$$w_1 = \sigma v_1 + \mu' x_1$$

instead of

$$u_1 = \frac{v_1 - \beta' x_1}{\sigma}.$$

The reparameterization offers two advantages:

- 1) Computation of the necessary partial derivatives is simple;
- 2) For maximum likelihood estimation with a logistic tolerance distribution, it can be shown that the regression parameterization results in a concave maximization problem. We anticipate that it will have fairly good properties in the more complicated cases.

It has a disadvantage in terms of potential ill-conditioning of the Hessian (or Jacobian) matrix, so that the input data should be sensibly scaled (see Section 11). Parameters are assumed to be expressed in the easier to understand location-scale form on entry, and are transformed back to location-scale form on exit, so the user need not worry about details of reparameterization.

Let

$$s_{\theta 1} = f^C(v_1) \left[a_1 \frac{\partial}{\partial \theta} \log F(v_1) + (1-a_1) \frac{\partial}{\partial \theta} \log S(v_1) \right].$$

The gradient used in Newton-Raphson iteration has θ^{th} component

$s_\theta = n^{-1} \sum_{i=1}^n s_{\theta i}$, and the Hessian has (θ, θ') component $s_{\theta \theta'} = n^{-1} \sum_{i=1}^n \frac{\partial}{\partial \theta} s_{\theta i}$,
(the scaling by n^{-1} should be helpful when n is large).

When $c = 0$, the estimated asymptotic covariance matrix of the estimators is $n^{-1}(-H)^{-1}$, while when $c \neq 0$ it is $n^{-1}H^{-1}VH^{-1}$, where V has (θ, θ') component

$V_{\theta\theta'} = n^{-1} \sum_{i=1}^n S_{ei}S_{e'i}$. The estimated asymptotic covariance matrix is expressed in location-scale form by pre- and post-multiplying it by the Jacobian of the underlying parameter transformation.

Newton-Raphson iteration converges when

$$\max_i | \theta^{(k)} - \theta_i^{(k-1)} | < ABSTOL$$

and

$$\max_i \left| \frac{\theta_i^{(k)}}{\theta_i^{(k-1)}} \right| < RELTOL,$$

where superscripts represent iteration numbers and ABSTOL and RELTOL are user-supplied. The user also specifies a maximum allowable number MAXIT of iterations.

Solution of linear equations and matrix inversion is accomplished by subroutines DECOMP and SOLVE, taken from Forsythe, Malcolm and Moler (1977). These routines are of high numerical quality, and provide an estimate of the condition number of the input matrix, which is often useful. In the interest of portability, iterative improvement is not used.

5. Parameters

5.1 Input Parameters

N - INTEGER
Sample size. Unchanged on exit.

IX - INTEGER
Row dimension of data matrix X. Unchanged on exit.

X - REAL array of DIMENSION (IX, q), where q ≥ N. Data matrix containing the dependent (stress) variable and all covariates. Each column corresponds to one observation. If parameters are held fixed, values of the dependent variable will be changed, but their input values restored.
Unchanged on exit.

IA - INTEGER array of DIMENSION N. Withstand or failure is indicated for observation I according as IA(I) = 0 or IA(I) ≠ 0.
Unchanged on exit.

NPAR - INTEGER. Number of parameters in the model.
Unchanged on exit.

ISUB - INTEGER array of DIMENSION (NPAR). Indicates rows of data matrix X corresponding to parameters (the scale parameter is taken to correspond to the dependent variable). For instance, if ISUB(3) = 5, the third parameter corresponds to the fifth row of X.
Unchanged on exit.

ISTART - INTEGER array of DIMENSION (NPAR). Indicates the status of parameters in the model, and whether a starting value is to be supplied.
If ISTART(I) is equal to
0, BETA(I) is to be estimated, and its input value is to be disregarded;
1, BETA(I) is to be estimated, and its input value is to be used as starting value;
2, BETA(I) is to be held constant at its input value.
(See Section 11.2 for comments on starting values; the scale of parameter is not allowed to be held constant.)
Unchanged on exit.

IDEP - INTEGER. Row of dependent (stress) variable in X.
Unchanged on exit.

IDIST - INTEGER. Indicates the tolerance distribution desired.
If IDIST equals
1, logistic distribution will be used;
2, Gaussian distribution will be used;
3, extreme value distribution will be used.
Unchanged on exit.

C - DOUBLE PRECISION User-supplied constant for self-critical estimation.
Unchanged on exit.

RELTOL - DOUBLE PRECISION.
Relative convergence tolerance for Newton-Raphson iteration
(see Section 4).
Unchanged on exit.

MAXIT - INTEGER.
Maximum allowable number of Newton-Raphson iteration.
Unchanged on exit.

IPRINT - INTEGER.
Output unit number. If IPRINT < 0, no output will be produced.
If IPRINT > 0, standard output will be produced on logical
output unit IPRINT.
Unchanged on exit.

IFLAG - INTEGER.
Indicator for form of output.
If IFLAG < 0, the standard output summary will be in regression
form. If IFLAG = 0, output summaries will be produced for
both regression and location-scale parameterizations. If
IFLAG > 0, the standard output summary will be in location-
scale form. (See Section 11.3).
Unchanged on exit.

5.2 Input/Output (and associated dimension) Parameters.

BETA - DOUBLE PRECISION array of DIMENSION (NPAR).
On entry, contains starting values as specified by ISTART.
On exit, contains parameter estimates, in location scale form.

XLOGL - DOUBLE PRECISION.
On exit, contains the log likelihood if c = 0 (maximum
likelihood estimation), and zero otherwise.

ICOV - INTEGER.
Row dimension for COV.
Unchanged on exit.

COV - DOUBLE PRECISION array of DIMENSION (ICOV, q), where q ≥ NPAR.
On exit, estimated asymptotic covariance information for the
parameters. The diagonal contains standard errors, the strict
lower triangle correlations, and the strict upper triangle
covariances. If a parameter is held constant, all correspond-
ing entries are zero. The covariance matrix will be for the
location-scale parameterization unless IFLAG < 0, when it will
be in regression form. See Section 11.3.

5.3 Workspace (and associated dimension) parameters

LMEM - INTEGER.
Length of work array MEMORY, as declared in calling program unit.
 $LMEM = NPAR + 4*NACT*(1+NACT) + 2*\max(NPIX, 2*NACT)$, where
NACT is the number of parameters estimated and $NPIX = NPAR - NACT$
is the number of parameters held constant.
Unchanged on exit.

MEMORY - INTEGER array of DIMENSION (LMEM).
Used as workspace.

5.4 Diagnostic Parameter

IPFAULT - INTEGER.
Unless the routine finds an error or gives a warning, IPFAULT
will be 0 on exit. See Section 6.

6. Error Indications and Warnings

Errors or warnings specified by the routine:

- IPFAULT < 0** If IPFAULT = -I, I > 0, then an arithmetic exception was about to occur on observation I, while computing partial derivatives. This failure should be rare. If the data have been sensibly scaled, and the starting values are not too bad (see Sections 11.1-11.2), the probable cause is a data error. The routine stops as soon as the error is detected, and output parameter values are not of interest.
- IPFAULT = -1** Input parameter outside expected range. This failure will occur if, on entry, $N < 1$, $NPAR < 1$, $IX < NPAR$, $ICOV < NPAR$, $RELTOL \leq 0$, $ABSTOL < 0$, $NACT < 1$, $IDIST < 1$, $IDIST > 3$, $IFLAG \leq 0$ and $IPRINT \leq 0$ (see Section 11.3), $ISTART(I) < 0$ or $ISTART(I) > 2$ for some I, $ISTART(I) = 2$ for all I, $ISUB(I) \neq IDEP$ for all I, or $ISUB(I) = IDEP$ and $ISTART(I) = 2$ for some I. (The last restriction means that the scale parameter cannot be held constant.) The routine stops without doing any calculations.
- IPFAULT = 2** Insufficient workspace. This failure will occur if, on entry, $LMEM < NPAR + 4*NACT*(1+NACT) + 2*\max(NPIX, 2*NACT)$, where NACT is the number of parameters estimated ($ISTART(I) < 2$), and $NPIX = NPAR - NACT$ is the number of parameters held constant ($ISTART(I) = 2$). The routine stops without doing any calculations.
- IPFAULT = 3** The Hessian matrix has become numerically singular during Newton-Raphson iteration. The routine transforms estimates to location-scale form, restores values of the dependent variable if parameters were held fixed, and stops. Output parameter values are not generally of interest.

IFAULT = 4 The Newton-Raphson iteration did not converge to within RELTOL and ABSTOL in the specified MAXIT iterations. The routine transforms estimates to location-scale form, restores values of the dependent variable if parameters were held fixed, and stops. Output parameter values are not generally of interest.

7. Auxiliary Routines

SUBROUTINE PREPAR(IX, N, X, NPAR, BETA, ISUB, ISTART, NACT, IACT, IMAP, PAR, NPIX, IFIXED, IDEP, WORK)

Prepares for iteration by setting up some indexing and working arrays, subtracting the effects of fixed parameters from the dependent variable, and setting initial active parameter values in regression form.

SUBROUTINE NEWTON(C, MAXIT, RELTOL, ABSTOL, DIFPER, XLOGL, NACT, IACT, PAR, IPIVOT, HESS, HESFAC, N, IX, X, IA, IPRINT, LWORK, WORK, LFAULT)

Carries out the Newton-Raphson iteration.

SUBROUTINE VARIAB(C, XLOGL, REGRES, DIFPER, VROUT, NACT, IACT, IMAP, PAR, IPIVOT, HESS, HESFAC, ICOV, NPAR, COV, DET, N, IX, X, IA, WORK)

Computes the estimated asymptotic covariance matrix, transforms it to location-scale form if requested, and computes correlations and standard errors.

SUBROUTINE EXPOST(REGRES, IDEP, NPAR, BETA, ISTART, NACT, PAR, IMAP, N, IX, X, NPIX, IFIXED, WORK)

Sets the output vector BETA, transforms to location-scale form if requested. If location-scale form is requested and parameters were held fixed, restore initial values of dependent variable.

SUBROUTINE RESULT (C, REGRES, IPRINT, IDIST, N, IDEP, NACT, NPIX, XLOGL, NPAR, BETA, ISUB, ISTART, ICOV, COV, DET)

Produces a standard output summary on logical output unit IPRINT.

The following routines are specific to particular tolerance distributions, and are declared EXTERNAL in BINARY. The first three, prefixed D, are passed to NENTON and VARIAB. The next three, prefixed V, are passed to VARIAB.

```
SUBROUTINE DLOGBN(C, OBJECT, NACT, IACT, PAR, GRAD, HESS, N, IX, X,  
IA,, IFAULT)  
SUBROUTINE DGAUBN ( ____ " ____ )  
SUBROUTINE DEXVBN ( ____ " ____ )
```

Compute gradient and Hessian for logistic, Gaussian and extreme value models, resp.

```
SUBROUTINE VLOGBN(C, NACT, IACT, PAR, V, N, IX, X, IA)  
SUBROUTINE VGAUBN(____ " ____ )  
SUBROUTINE VEXVBN(____ " ____ )
```

Compute V factor of estimated asymptotic covariance matrix for logistic, Gaussian and extreme value models, resp.

The following procedures perform general numerical tasks. They have been included in the interest of portability, although equivalents exist on many computer systems.

```
SUBROUTINE DECOMP(NDIM, N, A, UL, COND, INPUT, WORK)  
SUBROUTINE SOLVE(NDIM, N, A, B, X, INPUT)
```

DECOMP decomposes a matrix into LU factors and estimates its condition. SOLVE solves a linear system, using the results of DECOMP. These routines are in Forsythe, Malcolm and Moler (1977), but the present versions include an extra argument so that A and B need not be overwritten.

```
SUBROUTINE DMXNLT(A, IA, N1, B, IB, N2, C, IC, N3, WORK, LWORK,  
IFLAG, IFAULT)
```

Double precision matrix multiplication -
 $A(N1 \times N3) = B(N1 \times N2) * C(N2 \times N3)$, where B is overwritten if IFLAG < 0 and C is overwritten if IFLAG > 0.

```
DOUBLE PRECISION FUNCTION ALNORM (X, UPPER)  
Algorithm as 66 (Hill, 1973) to compute tail areas of the standard Normal curve.
```

```
DOUBLE PRECISION FUNCTION RMILLS(X)  
Computes  $Z(x)/Q(x)$ , the reciprocal of Mills' ratio, where x is a standard Normal variate. This procedure is based on procedures by Hill (1973) and Adams (1969).
```

8. References

Adams, A.G. (1969). Algorithm 39. Areas under the normal curve. Computer J., 12, 197-198.

Forsythe, G.E., Malcolm, M.A. and Moler, C.B. (1977). Computer Methods for Mathematical Computations. Englewood Cliffs, New Jersey: Prentice-Hall.

Hill, I.D. (1973). Algorithm AS 66. The normal integral. Applied Statistics, 22, 424-427.

Paulson, A.S., Presser, M.A. and Lawrence, C.E. (1983). Self-critical, and robust, procedures for the analysis of binary data. Operations Research and Statistics Report No. 37-83-P1, Department of Operations Research and Statistics, Rensselaer Polytechnic Institute.

9. Storage

There are no internally declared arrays.

10. Precision, Machine Dependent Constants

The routine was developed on an IBM computers. The data matrix is single precision to conserve storage. To convert to single precision, take the following steps, with the exception noted below:

- 1) Change all DOUBLE PRECISION declarations to REAL;
- 2) Replace references to double precision FORTRAN library functions with single precision versions, e.g., EXP replaces DEXP;
- 3) Replace double precision constants by their single precision versions, e.g., 1.0 replaces 1.0D0.

Note: In routines PREPAR and EXPOST, the dependent variable is adjusted for the effect of fixed parameters. These adjustments must be calculated in double precision

to avoid a loss of significant digits in X which could affect subsequent computations.

Procedures DLOGBN, VLOGBN, DGAUBN, VGAUBN, DEXUBN, VEXUBN, DECOMP, ALNORM and RMILLS use machine-dependent constants whose values are set in DATA statements. These constants may have to be altered for some computers. They are pointed out by comments in the program units.

11. Further Comments

11.1 Scaling, conditioning of Hessian matrix

The user should be aware of potential problems of ill-conditioning. Because a regression-type parameterization is used, calculation of the Hessian matrix involves operations similar to the formation of $X^T X$, where X is the data matrix. Unfortunately, the resulting Hessian is often rather ill-conditioned. If IPRINT > 0, an estimate of the Hessian's condition number is printed out at each iteration. Roughly speaking, a condition number in excess of 10^7 is worrisome, although condition numbers in excess of 10^{10} can be tolerated when working in double precision on an IBM 3081. The user can and should avoid potentially excessive ill-conditioning by scaling the data matrix X before calling the routine.

Although it is not known how to optimally scale a problem, it seems that a nearly ideal scaling will be achieved if nonconstant variables are transformed to the range [-1, 1], centered at zero. However, such precise scaling is often tedious. It seems most important to "equilibrate" the data matrix so that all variables have roughly the same (moderate) magnitude. Such equilibration is often simply accomplished by dividing by suitable powers of 10, e.g., expressing voltages in megavolts instead of kilovolts. Centering the variables will further reduce the condition number. One often centers covariates anyway, so that the "intercept"

parameter has a clear interpretation.

11.2. Starting values

Since Newton-Raphson procedure is employed, starting values are important. If no starting values are supplied by the user ($ISTART(I) = 0$ for all I), the routine will use unity for the scale parameter and zero for all location parameters. These starting values will not be acceptable unless the dependent variable has been centered and scaled. It is recommended that the user employ the mean and standard deviation of the dependent variable as starting values for the "intercept" parameter (if any) and scale parameter, respectively. If the model is sequentially refit with different values of c , it is recommended that estimates from the most recent call be used as starting values for the next call.

11.3 Output Flags

Because the routine will generally be called sequentially with different values of c , it is most convenient to always express entry and exit parameter values in the same form. The location-scale form is used, because that form affords the clearest interpretation. An inconsistency arises if $IFLAG < 0$, for then the output estimates are in location-scale form, but the covariance matrix is in regression form. Thus, if the user wants to make separate use of the output parameters of BINARY, the routine should be called with $IFLAG \geq 0$.

It is recommended that the routine be called with $IPRINT > 0$. If $IFLAG \leq 0$, the requirement $IPRINT > 0$ is enforced. (When $IFLAG < 0$, the requirement is in keeping with the inconsistency mentioned above.) The standard output summary should

be sufficient for most applications. For the maximum flexibility in output and interpretation of results, call BINARY with IPRINT > 0, IFLAG = 0.

12. Example

The following program illustrates the use of BINARY, and the standard output produced when IPRINT > 0 and IFLAG = 0.

```

C.....(OPTIONALLY ROBUST) BINARY DATA ESTIMATION ROUTINE
C LOGISTIC, EXTREME VALUE, OR GAUSSIAN TOLERANCE DISTRIBUTION
C CAN BE USED. PARAMETERS ON INPUT/OUTPUT ARE IN LOCATION-
C SCALE FORM. BUT ESTIMATION IS CARRIED OUT USING A
C REGRESSION-TYPE REPARAMETERIZATION. IF PRINTOUT IS DESIRED
C (IPRINT .GT. 0), RESULTS CAN BE PRINTED OUT IN REGRESSION
C FORM, LOCATION-SCALE FORM, OR BOTH. ARGUMENT IFLAG
C SPECIFIES THE OUTPUT DESIRED.
C
C FAILURE CODES
C
C   IFAULT = 1 - INPUT ERROR
C   IFAULT = 2 - INSUFFICIENT WORKSPACE SUPPLIED
C   IFAULT = 3 - HESSIAN MATRIX IS NUMERICALLY SINGULAR
C   IFAULT = 4 - NO CONVERGENCE IN MAXIT ITERATIONS
C   IFAULT = -1 - AN EXCEPTION WAS ABOUT TO OCCUR WHILE
C                 PROCESSING THE I TH OBSERVATION
C
C.....SUBROUTINE BINARY(N, IX, IA, NPAR, ISUB, ISTART, IDEP, IDIST,
C   1          C, RELTOL, ABSTOL, MAXIT, IPRINT, IFLAG, BETA, XLOGL,
C   2          ICOV, COV, LMEM, MEMORY, IFAULT)
C
C       EXTERNAL PROCEDURES FOR PARTICULAR TOLERANCE DISTRIBUTIONS
C
C       EXTERNAL DLOGBN, DGAUBN, DEXVBN, VLOGBN, VGAUBN, VEXVBN
C
C       ARGUMENTS
C
C       INTEGER N, IX, IAIN, NPAR, ISUB(NPAR), ISTART(NPAR), IDEP, IDIST, BINA001
C   1      MAXIT, IPRINT, IFLAG, ICOV, LMEM, MEMORY(LMEM), IFAULT
C   2      BINA002
C
C       REAL X(IX,N)
C
C       DOUBLE PRECISION C, RELTOL, ABSTOL, BETA(NPAR), XLOGL,
C   1      COV(ICOV,NPAR)
C
C       LOCAL SCALARS
C
C       LOGICAL REGRES
C
C       INTEGER NACT, NFIX, IND, INDI, MIACT, MIFIX, MIMAP, MIPVT, NPAR,
C   1      NMESS, NMFFAC, NWORK
C
C       DOUBLE PRECISION DET, ZERO
C
C       CONSTANTS
C
C       DATA ZERO / OODO/
C
C       CHECK FOR INPUT ERRORS
C
C       IFAULT = 1
C       IF (IN .LT. 1 .OR. NPAR .LT. 1 .OR. IX .LT. NPAR .OR. ICOV .LT.
C   1      NPAR) RETURN
C       IF (RELTOL .LE. ZERO .OR. ABSTOL .LE. ZERO .OR. MAXIT .LT. 1)
C   1      RETURN
C       IF ((IDIST .LT. 1 .OR. IDIST .GT. 3) .RETURN
C   1      IFLAG .LE. 0 .AND. IPRINT .LE. 0) RETURN
C
C       MEMORY MANAGEMENT, POSSIBLE RELATED INPUT ERRORS, CHECK
C
C       ISUB(*). ISTART(*) VECTORS. COUNT ACTIVE PARAMETERS.
C
C       NOTE SCALE PARAMETER CANNOT BE FIXED.
C
C       NACT = 0
C       IND1 = 0
C       DO 10 I = 1, NPAR
C   10      IND = ISUB(I)
C       IF (IND .LT. 1 .OR. IND .GT. IX) RETURN
C       IF (IND .EQ. IDEP) IND1 = 1
C       IND = ISTART(I)
C       IF (IND .LT. 0 .OR. IND .GT. 2) RETURN
C       IF (IND .NE. 2) NACT = NACT + 1
C
C       10 CONTINUE
C       IF (NACT .EQ. 0 .OR. IND1 .EQ. 0) RETURN
C       IF (ISUB(IND1) .EQ. 2) RETURN
C
C.....BINA001 BINA002 BINA003 BINA004 BINA005 BINA006 BINA007 BINA008
C.....BINA009 BINA010 BINA011 BINA012 BINA013 BINA014 BINA015 BINA016 BINA017
C.....BINA018 BINA019 BINA020 BINA021 BINA022 BINA023 BINA024 BINA025 BINA026
C.....BINA027 BINA028 BINA029 BINA030 BINA031 BINA032 BINA033 BINA034 BINA035
C.....BINA036 BINA037 BINA038 BINA039 BINA040 BINA041 BINA042 BINA043 BINA044
C.....BINA045 BINA046 BINA047 BINA048 BINA049 BINA050 BINA051 BINA052 BINA053
C.....BINA054 BINA055 BINA056 BINA057 BINA058 BINA059 BINA060

```

```

NFIIX = NPAR - NACT
C   CHECK IF WORKSPACE SIZE IS ADEQUATE. ALLOCATE IT
C
IFault = 2
IND = 2 * NACT
IND1 = IND + NACT
IF (LMEM .LT. NPAR + 2*NACT + IND + 2*IND1 + MAXO(2*NFIIX,2*IND)) BINA0065
  RETURN
  BINA0066
  BINA0067
  BINA0068
  BINA0069
  BINA0070
  BINA0071
  BINA0072
  BINA0073
  BINA0074
  BINA0075
  BINA0076
  BINA0077
  BINA0078
  BINA0079
  BINA0080
  BINA0081
  BINA0082
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  BINA0111
  BINA0112
  BINA0113
  BINA0114
  BINA0115
  BINA0116
  BINA0117
  BINA0118
  BINA0119
  BINA0120

C   PREPARE FOR ESTIMATION - SET UP SUBSCRIPT ARRAYS AND
C   STARTING VALUES FOR ACTIVE PARAMETERS. SUBTRACT EFFECT OF
C   FIXED PARAMETERS FROM DEPENDENT VARIABLE
C
CALL PREPAR(IX, N, X, NPAR, BETA, ISUB, ISTART, NACT,
  1      MEMORY(MIACT), MEMORY(MIPVT), MEMORY(MIPAR), NFIIX,
  2      MEMORY(MIHESS), IDEP, MEMORY(MWORK))
  BINA0078
  BINA0079
  BINA0080
  BINA0081
  BINA0082
  BINA0083
  BINA0084
  BINA0085
  BINA0086
  BINA0087
  BINA0088
  BINA0089
  BINA0090
  BINA0091
  BINA0092
  BINA0093
  BINA0094
  BINA0095
  BINA0096
  BINA0097
  BINA0098
  BINA0099
  BINA0100
  BINA0101
  BINA0102
  BINA0103
  BINA0104
  BINA0105
  BINA0106
  BINA0107
  BINA0108
  BINA0109
  BINA0110
  BINA0111
  BINA0112
  BINA0113
  BINA0114
  BINA0115
  BINA0116
  BINA0117
  BINA0118
  BINA0119
  BINA0120

C   NEWTON-RAPHSON ITERATION WITH EXTERNAL ROUTINE PASSED FOR
C   FIRST AND SECOND PARTIALS
C
IF (IDIST .EQ. 1) CALL NEWTON(C, MAXIT, RELTOL, ABSTOL, DLOGRN,
  1      XLOGL, NACT, MEMORY(MIPVT), MEMORY(MIPAR),
  2      MEMORY(MIHESS), MEMORY(MIACF), N, IX, X, IA, IPRINT, 2*NACT,
  3      MEMORY(MWORK)). IFAULT)
  BINA0085
  BINA0086
  BINA0087
  BINA0088
  BINA0089
  BINA0090
  BINA0091
  BINA0092
  BINA0093
  BINA0094
  BINA0095
  BINA0096
  BINA0097
  BINA0098
  BINA0099
  BINA0100
  BINA0101
  BINA0102
  BINA0103
  BINA0104
  BINA0105
  BINA0106
  BINA0107
  BINA0108
  BINA0109
  BINA0110
  BINA0111
  BINA0112
  BINA0113
  BINA0114
  BINA0115
  BINA0116
  BINA0117
  BINA0118
  BINA0119
  BINA0120

C   ERROR HANDLING IF NEWTON-RAPHSON PROCEDURE FAILS.
C   ON ERROR, PRINT OUT MESSAGE IF IPRINT .GT. 0, SET UP
C   THE FINAL CALL TO EXP01()
C
IF (IFault .EQ. 0) GO TO 30
  BINA0101
  BINA0102
  BINA0103
  BINA0104
  BINA0105
  BINA0106
  BINA0107
  BINA0108
  BINA0109
  BINA0110
  BINA0111
  BINA0112
  BINA0113
  BINA0114
  BINA0115
  BINA0116
  BINA0117
  BINA0118
  BINA0119
  BINA0120

C   COMPUTE APPROXIMATE ASYMPTOTIC COVARIANCE MATRIX.
C   REGRES IS A FLAG FOR WHETHER OR NOT TO SET UP OUTPUT IN
C   REGRESSION FORM. STATEMENT 30, THE FIRST BRANCH POINT,
C   SETS UP REGRES FOR FIRST OUTPUT (IF REGRESSION AND
C   LOCATION SCALE BOTH REQUESTED, REGRESSION GOES FIRST).
C   STATEMENT 40, THE SECOND BRANCH POINT, IS FOR REPEAT
C
GO TO 50
  BINA0101
  BINA0102
  BINA0103
  BINA0104
  BINA0105
  BINA0106
  BINA0107
  BINA0108
  BINA0109
  BINA0110
  BINA0111
  BINA0112
  BINA0113
  BINA0114
  BINA0115
  BINA0116
  BINA0117
  BINA0118
  BINA0119
  BINA0120

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C CALL (ALWAYS LOCATION-SCALE)
C   30 REGRES = IFLAG .LE. 0
C   40 IF (IDIST .EQ. 1) CALL VARIAB(C, XLOGL, REGRES, DLOGBN, VLOGBN,
C     1 NACT, MEMORY(MIACT), MEMORY(MIMAP), MEMORY(MIPAR)).
C     2 MEMORY(MIPVT), MEMORY(MHESS), MEMORY(MHFACT). ICOV, NPAR, COV, BINAO125
C     3 DET, N, IX, X, IA, MEMORY(MWORK)
C     4 IF (IDIST .EQ. 2) CALL VARIAB(C, XLOGL, REGRES, DGAUBN, VGAUBN,
C       1 NACT, MEMORY(MIACT), MEMORY(MIMAP), MEMORY(MIPAR)).
C       2 MEMORY(MIPVT), MEMORY(MHESS), MEMORY(MHFACT). ICOV, NPAR, COV, BINAO129
C       3 DET, N, IX, X, IA, MEMORY(MWORK)
C     4 IF (IDIST .EQ. 3) CALL VARIAB(C, XLOGL, REGRES, DEXVMN, VEXVMN,
C       1 NACT, MEMORY(MIACT), MEMORY(MIMAP), MEMORY(MIPAR)).
C       2 MEMORY(MIPVT), MEMORY(MHESS), MEMORY(MHFACT). ICOV, NPAR, COV, BINAO133
C       3 DET, N, IX, X, IA, MEMORY(MWORK)

C ARRANGE ESTIMATED PARAMETERS IN BETA(*) FOR OUTPUT
C IF LOCATION-SCALE FORM, TRANSFORM PARAMETERS AND POSSIBLY
C RESTORE DEPENDENT VARIABLE TO VALUE ON ENTRY
C 50 CALL EXPOST(REGRES, IDEP, NPAR, BETA, ISTART, NACT, MEMORY(MIPAR),
C     1 MEMORY(MIMAP), N, IX, X, NFIX, MEMORY(MIFIX), MEMORY(MWORK))
C
C IF (NEWTON-RAPHSON FAILED, GOODBYE.
C IF (IFAULT .NE. 0) RETURN
C
C PRODUCE STANDARD OUTPUT IF REQUESTED.
C IF (IPRINT .GT. 0) CALL RESULT(C, REGRES, IDIST, N, IDEP,
C     1 NACT, NFIX, XLOGL, NPAR, BETA, ISUB, ISTART, ICOV, COV, DET)
C
C IF OUTPUT DESIRED IN BOTH REGRESSION AND LOCATION-SCALE
C FORMS, LOOP BACK, ELSE EXIT
C REGRES = NOT REGRES
C IF ( NOT REGRES AND IFLAG .EQ. 0) GO TO 40
C
C IF ONLY REGRESSION FORM OUTPUT WAS REQUESTED, AN EXTRA
C CALL TO EXPOST() IS NEEDED TO RESTORE LOCATION-SCALE FORM
C IF (IFLAG .LT. 0) CALL EXPOST(REGRES, IDEP, NPAR, BETA, ISTART,
C     1 NACT, MEMORY(MIPAR), MEMORY(MIMAP), N, IX, X, NFIX,
C     2 MEMORY(MIFIX), MEMORY(MWORK))

C 60 FORMAT ('OFailure - EXCEPTION ON OBSERVATION NO. ', 15)
C 70 FORMAT ('OFailure - HESSIAN MATRIX IS NUMERICALLY SINGULAR')
C 80 FORMAT ('WARNING - NO CONVERGENCE IN', 14, 'ITERATIONS - POSSIBLBINAO162
C 1E FAILURE')
C
C END
C
C 60 FORMAT ('OFailure - EXCEPTION ON OBSERVATION NO. ', 15)
C 70 FORMAT ('OFailure - HESSIAN MATRIX IS NUMERICALLY SINGULAR')
C 80 FORMAT ('WARNING - NO CONVERGENCE IN', 14, 'ITERATIONS - POSSIBLBINAO162
C 1E FAILURE')
C
C RETURN
C
C PREP0001
C PREP0002
C PREP0003
C PREP0004
C PREP0005
C PREP0006
C PREP0007
C PREP0008
C PREP0009
C PREP0010
C PREP0011
C PREP0012
C PREP0013
C PREP0014
C PREP0015

C ALSO SUBTRACT EFFECTS OF FIXED PARAMETERS FROM DEPENDENT
C VARIABLE, USING WORK(*)
C NOTE - DEPENDENT VARIABLE (SCALE) PARAMETER IS ALWAYS
C PLACED FIRST IN PAR(*), FOR CONVENIENCE LATER
C
C SUBROUTINE PREPAR(IX, N, X, NPAR, BETA, ISUB, ISTART, NACT, IACT,
C     1 IMAP, PAR, NFIX, IFIXD, IDEP, WORK)
C
C ARGUMENTS

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INTEGER IX, N, NPAR, ISUB(NPAR), ISTART(NPAR), NACT, IACT(NACT).
      IMAP(NACT), NFIX, IFIXED(1), IDEP
REAL X(IX,N)
DOUBLE PRECISION BETA(NPAR), PAR(NACT), WORK(1)
LOCAL SCALARS
C INTEGER IND, IND1, LACT, ISCALE
DOUBLE PRECISION TEMP, ZERO, ONE
DATA ZERO, ONE /0.0D0, 1.0D0/
C C SET UP IACT(•), IFIXED(•), IMAP(•)
LACT = 0
IND = 0
ISCALE = 0
DO 20 I = 1, NPAR
  IF (ISTART(I) .EQ. 2) GO TO 10
  LACT = LACT + 1
  IMAP(LACT) = 1
  IND1 = ISUB(1)
  JACT(LACT) = IND1
  IF (IND1 .EQ. IDEP) ISCALE = 1
  GO TO 20
  IND = IND + 1
  IFIXED(IND) = ISUB(1)
  WORK(IND) = BETA(1)
20 CONTINUE
C C SWITCH PLACES SO SCALE IS FIRST ACTIVE PARAMETER
IND = IACT(1)
IACT(1) = IACT(ISCALE)
IACT(ISCALE) = IND
IND = IMAP(1)
IMAP(1) = IMAP(ISCALE)
IMAP(ISCALE) = IND
C C MAIN LOOP OVER SAMPLE IF PARAMETERS ARE FIXED, TO ADJUST
C DEPENDENT VARIABLE (TO BE RESET ON EXIT FROM BINARY())
IF (NFIIX .EQ. 0) GO TO 50
DO 40 I = 1, N
C C THE FOLLOWING INNER PRODUCT MUST BE ACCUMULATED IN DOUBLE
PRECISION
TEMP = DBLE(X(IDEF,1))
DO 30 J = 1, NFIIX
  IND = IFIXED(J)
  TEMP = TEMP - WORK(J) * X(IND,1)
30 CONTINUE
X(IDEF,1) = SNGL(TEMP)
C C 40 CONTINUE
C C SET STARTING VALUES
50 DO 60 I = 1, NPAR
  60 PAR(I) = ZERO
  TEMP = ONE
  IND = IMAP(1)
  IF (ISTART(IND) .EQ. 1 AND BETA(IND) .NE. ZERO) TEMP = BETA(IND)
  PAR(1) = ONE / TEMP
  IF (NACT .EQ. 1) RETURN
  DO 70 I = 2, NACT
    IND = IMAP(I)
    PREP0016
    PREP0017
    PREP0018
    PREP0019
    PREP0020
    PREP0021
    PREP0022
    PREP0023
    PREP0024
    PREP0025
    PREP0026
    PREP0027
    PREP0028
    PREP0029
    PREP0030
    PREP0031
    PREP0032
    PREP0033
    PREP0034
    PREP0035
    PREP0036
    PREP0037
    PREP0038
    PREP0039
    PREP0040
    PREP0041
    PREP0042
    PREP0043
    PREP0044
    PREP0045
    PREP0046
    PREP0047
    PREP0048
    PREP0049
    PREP0050
    PREP0051
    PREP0052
    PREP0053
    PREP0054
    PREP0055
    PREP0056
    PREP0057
    PREP0058
    PREP0059
    PREP0060
    PREP0061
    PREP0062
    PREP0063
    PREP0064
    PREP0065
    PREP0066
    PREP0067
    PREP0068
    PREP0069
    PREP0070
    PREP0071
    PREP0072
    PREP0073
    PREP0074
    PREP0075

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PREP0078 IF (ISTART(IND) .EQ. 1) = -BETA(IND) / TEMP
PREP0079 RETURN
PREP0080 END
PREP0081 C
PREP0082 C NEWTON-RAPHSON ITERATION
PREP0083 C FAILURE CODES -
PREP0084 C IFAULT = 1 - INSUFFICIENT WORKSPACE (LESS THAN 2 * NACT
PREP0085 C LOCATIONS)
PREP0086 C IFAULT = 2 - THE HESSIAN MATRIX IS NUMERICALLY SINGULAR
PREP0087 C IFAULT = 3 - CONVERGENCE HAS NOT OCCURRED IN MAXIT ITNS
PREP0088 C IFAULT = -1 - AN EXCEPTION WAS ABOUT TO OCCUR WHILE
PREP0089 C PROCESSING THE 1 TH OBSERVATION IN DIFFER()
PREP0090 C
PREP0091 C SUBROUTINE NEWTON(C, MAXIT, RELTOL, ABSTOL, XLOGL, NACT,
PREP0092 C 1 IACT, PAR, IPivot, HESS, HESFAC, N, IX, IA, IPRINT,
PREP0093 C 2 LWORK, WORK, IFAULT)
PREP0094 C ARGUMENTS - DIFFER IS EXTERNAL ROUTINE FOR PARTIALS
PREP0095 C INTEGER MAXIT, NACT, IACT(NACT), IPIVOT(NACT), N, IX, IA(N),
PREP0096 C IPRINT, LWORK, IFAULT
PREP0097 C REAL X(IX,N)
PREP0098 C DOUBLE PRECISION C, RELTOL, ABSTOL, XLOGL, PAR(NACT),
PREP0099 C 1 HESS(NACT,NACT), HESFAC(NACT,NACT), WORK(LWORK)
PREP0100 C LOCAL SCALARS
PREP0101 C INTEGER ITER, IND
PREP0102 C DOUBLE PRECISION GNORM, COND, ABSERR, RELLERR, TEMP, XNEW, ZERO,
PREP0103 C ONE
PREP0104 C DATA ZERO, ONE /0.0D0, 1.0D0/
PREP0105 C
PREP0106 C IFAULT = 1
PREP0107 C IF (LWORK .LT. 2*NACT) RETURN
PREP0108 C IFAULT = 0
PREP0109 C IND = NACT + 1
PREP0110 C ITER = 0
PREP0111 C IF (IPRINT .GT. 0) WRITE (IPRINT,50) C, MAXIT, RELTOL, ABSTOL
PREP0112 C LOOPING POINT FOR ITERATION - THE FIRST NACT LOCATIONS OF
PREP0113 C WORK(*) ARE USED FOR GRADIENT/INCREMENT. WHILE THE NEXT
PREP0114 C NACT LOCATIONS ARE WORKSPACE FOR DECOMP
PREP0115 C 10 ITER = ITER + 1
PREP0116 C CALL DIFFER(C, XLOGL, NACT, IACT, PAR, WORK(1), HESS, N, IX, X,
PREP0117 C 1A, IFAULT)
PREP0118 C IF (IAULT LT 0) RETURN
PREP0119 C
PREP0120 C FACTOR THE HESSIAN INTO L * U, CHECK IF SINGULAR
PREP0121 C CALL DECOMP(NACT, NACT, HESS, HESFAC, COND, IPIVOT, WORK(IND))
PREP0122 C IF (COND .NE. COND) GO TO 20
PREP0123 C IFAULT = 2
PREP0124 C RETURN
PREP0125 C
PREP0126 C SOLVE THE SYSTEM HESS * INCREMENT = -GRADIENT.
PREP0127 C OVERWRITING GRADIENT
PREP0128 C 20 GNORM = ZERO
PREP0129 C DO 30 I = 1, NACT
PREP0130 C TEMP = WORK(1)
PREP0131 C WORK(1) = -TEMP
PREP0132 C GNORM = GNORM + TEMP * TEMP
PREP0133 C CONTINUE
PREP0134 C DSORT(GNORM)
PREP0135 C

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CALL SOLVE(NACT, NACT, HESSAC, WORK, IPIVOT)
C
C      INCREMENT PARAMETERS, COMPUTE CONVERGENCE CRITERIA
      RELERR = ZERO
      ABSERR = ZERO
      DO 40 I = 1, NACT
        TEMP = WORK(I)
        ABSERR = DMAX1(ABSERR, DABS(TEMP))
        XNEW = PAR(I) + TEMP
        PAR(I) = XNEW
        IF (ONE + XNEW) NE. ONE) TEMP = TEMP / XNEW
        RELERR = DMAX1(RELERR, DABS(TEMP))
40 CONTINUE
      IF (IPRINT .GT. 0) WRITE (IPRINT,60) ITER, GNORM, RELERR, ABSERR,
     1COND
C
C      CHECK CONVERGENCE. SET FAILURE CODE IF NONE
      IF (RELERR .LT. RELTOL .AND. ABSERR .LT. ABSTOL) RETURN
      IF (ITER .LT. MAXIT) GO TO 10
      IF (FAULT = 3)
C
      50 FORMAT ('1      C      MAX ITNS  REL TOLER  ABS TOLER' /D11.3, 19,
     1      2D11.2)
      60 FORMAT ('0  ITN  GRAD NORM  REL CHANGE  ABS CHANGE' /15, 3D12.2, /, 1,
     1      ' , ESTIMATED CONDITION NUMBER OF HESSIAN IS', D10.2)
      RETURN
      END
C*****COMPUTATIONS FOR VARIABILITY OF THE ESTIMATORS.
C*****ESTIMATE ASYMPTOTIC COVARIANCE MATRIX, TRANSFORM IT FROM
C*****REGRESSION TO LOCATION-SCALE FORM, COMPUTE ASYMPTOTIC
C*****CORRELATIONS AND STD. ERRORS.
C*****SUBROUTINE VARIABLE(C, XLOGL, REGRES, DIFFER, VROUT, NACT,
C*****      IMAP, PIVOT, HESS, HESFAC, 1COV, NPAR, COV, DET,
C*****      N, IX, X, IA, WORK)
C
C      ARGUMENTS - DIFFER AND VROUT ARE SUBROUTINES
C      LOGICAL REGRES
      INTEGER NACT, JACT(NACT), IMAP(NACT), IPIVOT(NACT),
     1      IX, IA(N)
      REAL X(IX,N)
      DOUBLE PRECISION C, XLOGL, PAR(NACT), HESS(NACT,NACT),
     1      HESFAC(NACT,NACT), COV(1COV,NPAR), DET, WORK(NACT)
C
C      LOCAL SCALARS
      LOGICAL FLAG
      INTEGER IND, IND1, IND2
      DOUBLE PRECISION ALPHA, ALPHA2, TEMP, TEMP1, ZERO, ONE, SMALL
      MACHINE-DEPENDENT CONSTANT - SMALL SET SO THAT DEXP(X)
      WILL CAUSE EXCEPTION IF X LT. SMALL
      DATA ZERO, ONE, SMALL /0 0.0, 1 0.0, -180 000/
C
C      CALCULATE HESSIAN AT OPTIMAL POINT AND FACTOR IT
      (THIS MAY BE WASTEFUL IN SOME CASES, BUT IT AVOIDS
      SOME LOGICAL COMPLICATIONS.) WORK(*) USED AS SCRATCH
      THE HESSIAN IS ASSUMED NONSINGULAR, AS IT SHOULD BE IF
      THIS POINT IS REACHED FACTORIZATION TO HESFAC(*, *)
      CALL DIFFER(C, XLOGL, NACT, JACT, PIVOT, HESS, N, IX, X, IA,
     1      IND)
      CALL DECOMP(NACT, NACT, HESS, HESFAC, TEMP, IPIVOT, WORK)
C

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C   INVERT NEGATIVE OF HESSIAN. USING IPIVOT(•) AND
C   FACTORIZATION IN HESFAC(•,•). PLACE INVERSE IN HESS(•,•)
DO 20 J = 1, NACT
  DO 10 I = 1, NACT
    HESS(I,J) = ZERO
    HESS(J,J) = -ONE
    CALL SOLVE(NACT, NACT, HESFAC, HESS(1,J), HESS(1,J), IPIVOT)
20 CONTINUE
IF (IC EQ ZERO) GO TO 30

C   SECTION FOR ROBUST ANALYSIS -
C   PLACE PRODUCT (H INVERSE) * V * (H INVERSE) IN HESS(•,•)
C   FIRST COMPUTE VI(•,•), PLACE IN COV(•,•)
C   CALL VROUT(C, NACT, IACT, PAR, COV, N, IX, X, IA)

C   MULTIPLY HESS * COV. OVERWRITING COV(•,•)
C   CALL DMXMLT(COV, NACT, NACT, HESS, NACT, COV, NACT, NACT)
1   WORK, NACT, 1, IND)

C   MULTIPLY COV * HESS. OVERWRITING HESS(•,•)
C   CALL DMXMLT(HESS, NACT, NACT, COV, NACT, HESS, NACT, NACT,
1   WORK, NACT, 1, IND)

C   ALL VALUES OF C - IF LOCATION-SCALE FORM. TRANSFORM
C   THE COVARIANCE MATRIX.
C   30 IF (REGRES) GO TO 80
  ALPHA = PAR(1)
  ALPHA2 = ALPHA * ALPHA
  FLAG = NACT EQ 1

C   LEFT-MULTIPLY HESS(•,•) BY JACOBIAN. RESULT TO HESFAC(•,•)
DO 50 J = 1, NACT
  TEMP = HESS(1,J) / ALPHA2
  HESFAC(1,J) = -TEMP
  IF (FLAG) GO TO 50
  DO 40 I = 2, NACT
    HESFAC(I,J) = PAR(I) * TEMP - HESS(I,J) / ALPHA
40   HESFAC(I,J) = PAR(I) * TEMP - HESFAC(I,J) / ALPHA
50 CONTINUE

C   RIGHT-MULTIPLY HESFAC(•,•) BY TRANPOSE OF JACOBIAN.
C   RESULT TO HESS(•,•)
DO 70 I = 1, NACT
  TEMP = HESFAC(I,1) / ALPHA2
  HESS(I,1) = -TEMP
  IF (FLAG) GO TO 70
  DO 60 J = 2, NACT
    HESS(I,J) = PAR(J) * TEMP - HESFAC(I,J) / ALPHA
60   HESS(I,J) = PAR(J) * TEMP - HESS(I,J) / ALPHA
70 CONTINUE

C   BOTH PARAMETERIZATIONS - DIVIDE COVARIANCE MATRIX BY
C   SAMPLE SIZE
C   80 TEMP = DBLE(FLOAT(N))
DO 90 J = 1, NACT
  DO 90 I = 1, J
    HESS(I,J) = HESS(I,J) / TEMP
    HESS(J,I) = HESS(I,J) / TEMP
90 CONTINUE

C   FIND DETERMINANT OF COVARIANCE MATRIX - FACTOR IT.
C   RESETTING IPIVOT(•) AND HESFAC(•,•)
C   VAR10034
  VAR10035
  VAR10036
  VAR10037
  VAR10038
  VAR10039
  VAR10040
  VAR10041
  VAR10042
  VAR10043
  VAR10044
  VAR10045
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  VAR10093

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CALL DECOMP(NACT, NACT, HESS, HESFAC, TEMP, IPIVOT, WORK)
DET = ZERO
IF (TEMP + ONE EQ TEMP) GO TO 110
IND = IPIVOT(NACT)
DO 100 I = 1, NACT
  TEMP1 = HESFAC(I,1)
  IF (ITEMP1 LT ZERO) IND = -IND
  DET = DET + DLOG(DABS(ITEMP1))
100 CONTINUE

C   TAKE THE NACT ROOT OF DETERMINANT. SET DET TO ZERO
C   IF IT UNDERFLOWS OR IS NEGATIVE
  DET = DET / DBLE(FLOAT(NACT))
  IF (DET LT SMALL OR IND LT 0) DET = ZERO
  IF (DET GE SMALL AND IND GT 0) DET = DEXP(DET)

C   MOVE CONTENTS OF HESS(*,*) TO UPPER TRIANGLE OF COV(*,*)
  110 DO 120 J = 1, NPAR
    DO 120 I = 1, NPAR
      120 COV(I,J) = ZERO
      DO 130 I = 1, NACT
        IND = IMAP(I)
        DO 130 J = 1, NACT
          IND1 = IMAP(J)
          IND2 = MIN(IND,IND1)
          IND1 = MAX(IND,IND1)
          COV(IND2,IND1) = HESS(I,J)
130 CONTINUE

C   PUT STD ERRORS ON DIAG OF COV(*,*). CORRELATIONS BELOW
  DO 150 I = 1, NPAR
    TEMP = COV(I,I)
    IF (ITEMP EQ ZERO) GO TO 150
    TEMP = DSQRT(ITEMP)
    COV(I,I) = TEMP
    IF (I EQ 1) GO TO 150
    IND = 1
    DO 140 J = 1, IND
      TEMP1 = COV(J,J)
      IF (ITEMP1 NE ZERO) COV(I,J) = COV(J,I) * (ITEMP * TEMP1)
140 CONTINUE
150 CONTINUE

C   RETURN
END

C***** EX POST ADJUSTMENTS BEFORE EXIT
C***** PUT OPTIMAL PARAMETERS IN BETA(*). IF LOCATION-SCALE
C***** FORM, TRANSFORM THE PARAMETERS AND RESTORE DEPENDENT
C***** VARIABLE TO INITIAL VALUES IF PARAMETERS WERE FIXED.
C***** SUBROUTINE EXPOST(IREGRES, IDEP, NPAR, BETA, ISTART, PAR,
C***** , IMAP, N, IX, NFIX, IFIXED, WORK)
C   ARGUMENTS
C   LOGICAL REGRES
C   INTEGER IDEP, NPAR, ISTART(NPAR), NACT, IMAP(NACT), N, IX, NFIX,
C   , IFIXED(1)
C   REAL X(IX,N)
C   DOUBLE PRECISION BETA(NPAR), PAR(NACT), WORK(1)
C   LOCAL SCALARS

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INTEGER IND
DOUBLE PRECISION TEMP, ONE
DATA ONE /1 000/
C
C      INSERT WORKING PARAMETERS PAR(*) IN BETA(*). IN THE
C      SUITABLE FORM.
C      TEMP * PAR(1)
IND = IMAP(1)
IF (REGRES) BETA(IND) = TEMP
IF ( NOT REGRES) BETA(IND) = ONE / TEMP
IF (INACT EQ 1) GO TO 20
DO 10 I = 2, NACT
IND = IMAP(I)
IF (REGRES) BETA(IND) = PAR(I)
IF ( NOT REGRES) BETA(IND) = -PAR(I) / TEMP
10 CONTINUE
C
C      IF LOCATION SCALE FORM AND PARAMETERS WERE HELD FIXED,
C      RESTORE DEPENDENT VARIABLE
C      20 IF (REGRES OR NFIX .EQ. 0) RETURN
IND = 0
DO 30 I = 1, NPAR
IF (ISTART(I) NE 2) GO TO 30
IND = IND + 1
WORK(IND) = BETA(I)
30 CONTINUE
DO 50 I = 1, N
C
C      THE FOLLOWING INNER PRODUCT MUST BE ACCUMULATED IN DOUBLE
C      PRECISION
TEMP = DBLE(X(1DEP,I))
DO 40 J = 1, NFIX
IND = 1FIXED(IJ)
TEMP = TEMP + WORK(J) * X(IND,J)
40 CONTINUE
X(1DEP,I) = SNGL(TEMP)
50 CONTINUE
C
C      RETURN
END
C*** PRINT OUT TYPICAL OUTPUT SUMMARY ON OUTPUT UNIT IPRINT
C*** SUBROUTINE RESULT(C, REGRES, IPRINT, IDIST, N, IDEP, NACT, NFIX,
1          XLGGL, NPAR, BETA, ISUB, ISTART, ICOV, COV, DET)
C
C      ARGUMENTS
C      LOGICAL REGRES
INTEGER IPRINT, IDIST, N, IDEP, NACT, NPAR, ISUB(NPAR),
1          ISTART(NPAR), ICOV
DOUBLE PRECISION C, XLGGL, BETA(NPAR), COV(ICOV, NPAR), DET
C
C      LOCAL SCALARS
LOGICAL MLE
INTEGER IND
DOUBLE PRECISION TSTAT, ZERO
DATA ZERO /0 000/
C
C      BASIC HEADINGS
C      MLE = C EQ ZERO
      IF (MLE) WRITE (IPRINT, 40)

```



```

IF ( NOT MLE) WRITE (IPRINT,50) C
IF (IDIST EQ 1) WRITE (IPRINT,60)
IF (IDIST EQ 2) WRITE (IPRINT,70)
IF (IDIST EQ 3) WRITE (IPRINT,80)
WRITE (IPRINT,90) N,NACT,NACT,NFIX
IF (REGRES) WRITE (IPRINT,100)
IF ( NOT REGRES) WRITE (IPRINT,110)

C
C PARAMETER ESTIMATES
WRITE (IPRINT,120)
DO 20 I = 1, NPAR
  IND = 1SUB(I)
  IF (ISTART(I) LT 2) GO TO 10
  WRITE (IPRINT,130) I, IND, BETA(I)
  GO TO 20
10  ISTAT = BETA(I) / COV(I,I)
  IF (IND EQ IDEP) WRITE (IPRINT,140) I, IND, BETA(I), COV(I,I), RESU036
  IF (IND NE IDEP) WRITE (IPRINT,150) I, IND, BETA(I), COV(I,I), RESU037
  ISTAT
  ISTAT
20 CONTINUE

C
C ASYMPTOTIC QUANTITIES
IF (MLE) WRITE (IPRINT,160) XLOGL
IF (DET LE ZERO) WRITE (IPRINT,170)
IF (DET GT ZERO) WRITE (IPRINT,180) NACT, DET
WRITE (IPRINT,190)
DO 30 J = 1, NPAR
30 WRITE (IPRINT,200) (COV(I,J), J=1,1)

C
40 FORMAT ('MAXIMUM LIKELIHOOD BINARY ANALYSIS')
50 FORMAT ('SELF-CRITICAL BINARY ANALYSIS. C = ', D11.3)
60 FORMAT ('LOGISTIC TOLERANCE DISTRIBUTION')
70 FORMAT ('GAUSSIAN TOLERANCE DISTRIBUTION')
80 FORMAT ('EXTREME VALUE TOLERANCE DISTRIBUTION')
90 FORMAT ('ANALYSIS OF ', 16, ' CASES AND ', 14, ' VARIABLES', '/O',
14, ' PARAMETERS WERE ESTIMATED AND ', 14,
2, ' WERE HELD CONSTANT', 21, 'O')
100 FORMAT ('PARAMETERS ARE EXPRESSED IN REGRESSION FORM', '/O')
110 FORMAT ('PARAMETERS ARE EXPRESSED IN LOCATION SCALE FORM', '/O')
120 FORMAT (' ', 1, 'VAR', 8X, 'BETA(I)', 6X, 'STD ERR', 9X,
1, 'STAT', 5X, 'STATUS')

130 FORMAT (215, 015, 7, 35X, 'FIXED LOCATION')
140 FORMAT (215, 3015, 7, 5X, 'ESTIMATED SCALE')
150 FORMAT (215, 3015, 7, 5X, 'ESTIMATED LOCATION')
160 FORMAT (21/, 0/, 1/, 'THE LOG LIKELIHOOD IS', D16.8)
170 FORMAT (21/, 0/, 1/, 'THE ESTIMATED ASYMPTOTIC COVARIANCE',
1, 'MATRIX IS NOT POSITIVE DEFINITE')
180 FORMAT (21/, 'O', 1/, 'THE', 14, ' ROOT OF THE DETERMINANT',
1, 'OF THE ESTIMATED', 'ASYMPTOTIC COVARIANCE MATRIX IS',
2, D16.8)
190 FORMAT (1/, 'ESTIMATED ASYMPTOTIC STD ERRORS (ON DIAGONAL',
1, 'CORRELATIONS (BELOW DIAGONAL)', ' ')
200 FORMAT (10012, 4)
RETURN
END
.....C.....FIRST AND SECOND PARTIAL DERIVATIVES FOR LOGISTIC BINARY.
.....C.....REGRESSION PARAMETERIZATION PARTIALS ARE SCALED BY
.....C.....SAMPLE SIZE
.....C.....DLOG0001
.....C.....DLOG0002
.....C.....DLOG0003
.....C.....DLOG0004

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```

DDENS = X(J) * EITHER
GRAD(J) = GRAD(J) + DDENS
DOENS = X(J) * (S - F)
IF (J .EQ. 1) DOENS = DDENS + EXTRA
DOENS = DOENS * FC - G * X(J)
DO 70 K = J, NACT
IND = IACT(K)
HESS(K,J) = HESS(K,J) + X(IND,1) * DDENS
CONTINUE
70 CONTINUE
80 CONTINUE
90 CONTINUE

C   SCALE GRADIENT AND HESSIAN BY SAMPLE SIZE
EXTRA = DBLE(FLOAT(N))
DO 100 J = 1, NACT
GRAD(J) = GRAD(J) / EXTRA
DO 100 I = J, NACT
HESS(I,J) = HESS(I,J) / EXTRA
HESS(J,I) = HESS(I,J)
100 CONTINUE
FAULT = 0
RETURN

C   ERROR EXIT
110 IFault = -1
C
RETURN
END

C*****COMPUTE V(*,* ) FACTOR FOR ASYMPTOTIC COVARIANCE MATRIX.
C*****LOGISTIC BINARY. CALLED ONLY WHEN C .NE. 0.
C*****SUBROUTINE VLOGBN(C, NACT, IACT, PAR, V, N, IX, IA)
C   ARGUMENTS
C   INTEGER NACT, IACT(NACT), N, IX, IA(N)
C   REAL X(IX,N)
C   DOUBLE PRECISION C, PAR(NACT), V(NACT,NACT)
C   LOCAL SCALARS
C   INTEGER IND
C   DOUBLE PRECISION FC, S, F, EITHER, TEMP, ZERO, ONE, BIG
C   MACHINE-DEPENDENT CONSTANT - BIG ROUGHLY CHOSEN SO THAT
C   DEXP(X) WILL CAUSE EXCEPTION IF /X/ .GT. BIG
C   DATA ZERO, ONE, BIG /0.0D0, 1.0D0, 1.74.D00/
C
C   SET UPPER TRIANGLE OF V(*,*) TO 0
DO 10 J = 1, NACT
DO 10 I = J, NACT
10 V(I,J) = ZERO

C   MAIN LOOP OVER SAMPLE
DO 50 I = 1, N
FC = ZERO
DO 20 J = 1, NACT
IND = IACT(J)
FC = FC + PAR(J) * X(IND,1)
20 CONTINUE
IF (DABS(FC) .GE. BIG) GO TO 50
FC = DEXP(FC)
S = ONE + FC
F = FC / S
VLOG0001
VLOG0002
VLOG0003
VLOG0004
VLOG0005
VLOG0006
VLOG0007
VLOG0008
VLOG0009
VLOG00091
VLOG00092
VLOG00010
VLOG0011
VLOG0012
VLOG0013
VLOG0014
VLOG0015
VLOG0016
VLOG0017
VLOG0018
VLOG0019
VLOG0020
VLOG0021
VLOG0022
VLOG0023
VLOG0024
VLOG0025
VLOG0026
VLOG0027
VLOG0028
VLOG0029
VLOG0030
VLOG0031
VLOG0032

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VLOG0034 VLOG0035 VLOG0036 VLOG0037 VLOG0038 VLOG0039 VLOG0040 VLOG0041 VLOG0042 VLOG0043 VLOG0044 VLOG0045 VLOG0046 VLOG0047 VLOG0048 VLOG0049 VLOG0050 VLOG0051 VLOG0052 VLOG0053 VLOG0054 VLOG0055 VLOG0056 VLOG0057 VLOG0058 VLOG0059 VLOG00001 VLOG00002 VLOG00003 VLOG00004 VLOG00005 VLOG00006 VLOG00007 VLOG00008 VLOG00009 VLOG00010 VLOG00011 VLOG00012 VLOG00013 VLOG00014 VLOG00015 VLOG00016 VLOG00017 VLOG00018 VLOG00019 VLOG00020 VLOG00021 VLOG00022 VLOG00023 VLOG00024 VLOG00025 VLOG00026 VLOG00027 VLOG00028 VLOG00029 VLOG00030 VLOG00031 VLOG00032

C      S = ONE / S
C      FC = (FS) •• C
C      EITHER = S
C      IF (IA(1) .EQ. 0) EITHER = F
C      EITHER = (EITHER*FC) •• 2
C
C      INCREMENT TERM OF V(•,•)
C      DO 40 J = 1, NACT
C          IND = IACT(J)
C          TEMP = EITHER * X(IND,1)
C          DO 30 K = J, NACT
C              IND = IACT(K)
C              V(K,J) = V(K,J) + TEMP * X(IND,1)
C
C      30      CONTINUE
C      40      CONTINUE
C      50      CONTINUE
C
C      DIVIDE V(•,•) BY SAMPLE SIZE. FILL OUT
C      TEMP = DBLE(FLOAT(N))
C      DO 60 J = 1, NACT
C          DO 60 I = 1, J, NACT
C              V(I,J) = V(I,J) / TEMP
C              V(J,I) = V(I,J)
C
C      60      CONTINUE
C
C      RETURN
CEND

C***** FIRST AND SECOND PARTIAL DERIVATIVES FOR BINARY GAUSSIAN.
C***** REGRESSION PARAMETERIZATION PARTIALS ARE SCALED BY
C***** SAMPLE SIZE
C***** FAILURE CODE - IFAULT = 1 - AN EXCEPTION WAS ABOUT TO
C***** OCCUR WHILE PROCESSING THE 1 TH OBSERVATION
C***** SUBROUTINE DGAUBN(C, OBJECT, NACT, PAR, GRAD, MESS, N, IX,
C      1      X, IA, IFAULT)
C      1      ARGUMENTS
C      1      INTEGER NACT, IACT(NACT), N, IX, IA(N), IFAULT
C      1      REAL X(IX,N)
C      DOUBLE PRECISION C, OBJECT, PAR(NACT), GRAD(NACT), HESS(NACT,NACT)
C      LOCAL SCALARS
C      LOGICAL MLE
C      INTEGER IND
C      DOUBLE PRECISION EXTRA, DOTMIN, FC, CBY2, RATIO, EITHER,
C      1      HTERM, XJ1, DDENS, ZERO, ONE, TWO, BIG
C      FUNCTIONS CALLED
C      DOUBLE PRECISION ALNORM, RMILLS
C      MACHINE-DEPENDENT CONSTANT - BIG ROUGHLY CHOSEN SO THAT
C      DEXP(X) WILL CAUSE EXCEPTION IF /X/ .GT. BIG
C      DATA ZERO, ONE, TWO, BIG /O OOO, 1.000, 2.000, 174.000/
C
C      IFAULT = 0
C      MLE = ONE + C .EQ. ONE
C      EXTRA = ONE / PAR(1)
C      CBY2 = C / TWO
C      OBJECT = ZERO
C      DO 10 J = 1, NACT
C          GRAD(J) = ZERO
C
C      10      CONTINUE
C      10      MESS(1) = ' '
C      10      NACT = 1
C      10      BIG = 1.7E+30
C
C      10      CONTINUE
C      10      RETURN
CEND

```

```

10 CONTINUE
C   MAIN LOOP OVER SAMPLE
C   DO 90 1 = 1, N
C     DOT = ZERO
C     DO 20 J = 1, NACT
C       IND = IACT(J)
C       DOT = DOT + PAR(J) * X(IND,1)
C 20  CONTINUE
C   DOTMIN = -DOT
C   IF (IA(1) .EQ. 0) GO 10 30
C   RATIO = RMILLS(DOTMIN)
C   EITHER = RATIO
C   GO 10 40
C   RATIO = RMILLS(DOT)
C   DOT = DOTMIN
C   EITHER = -RATIO
C   IF (MLE) GO 10 50
C   XJI = CBY2 * DOT * DOT
C   IF (DABS(XJI) .GT. BIG) GO 10 110
C   FC = DEXP(-XJI)
C   GO 10 60
C   FC = ONE
C   XJI = ALNORM(DOT, .FALSE.)
C   IF (XJI .EQ. ZERO) GO 10 110
C   OBJECT = OBJECT + DLOG(XJI)
C
C   INCREMENT GRADIENT AND HESSIAN
C   EITHER = FC * EITHER
C   HTERM = -FC * RATIO * (DOT + RATIO)
C   FC = C * EITHER
C   DO 80 J = 1, NACT
C     IND = IACT(J)
C     XJI = DBLE(X(IND,1))
C     GRAD(J) = GRAD(J) + XJI * EITHER
C     DDENS = XJI * DOTMIN
C     IF (J .EQ. 1) DDENS = DDENS + EXTRA
C     DDENS = DDENS * FC * XJI * HTERM
C     DO 70 K = J, NACT
C       IND = IACT(K)
C       HESS(K,J) = HESS(K,J) + X(IND,1) * DDENS
C 70  CONTINUE
C 80  CONTINUE
C 90  CONTINUE
C
C   SCALE GRADIENT AND HESSIAN BY SAMPLE SIZE
C   EXTRA = DBLE(FLOAT(N))
C   DO 100 J = 1, NACT
C     GRAD(J) = GRAD(J) / EXTRA
C   DO 100 1 = J, NACT
C     HESS(1,J) = HESS(1,J) / EXTRA
C     HESS(1,1) = HESS(1,1)
C 100 CONTINUE
C   IF AULT = 0
C   RETURN
C
C   ERROR EXIT
C   110  IF AULT = -1
C
C   RETURN

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```

C..... END
C..... COMPUTE V(.,.) FACTOR FOR ASYMPTOTIC COVARIANCE MATRIX.
C..... GAUSSIAN BINARY CALLED ONLY WHEN C .NE. 0
C..... .....VGAU0001 .....VGAU0002 .....VGAU0003 .....VGAU0004 .....VGAU0005 .....VGAU0006 .....VGAU0007 .....VGAU0008 .....VGAU0009 .....VGAU0010 .....VGAU0011 .....VGAU0012 .....VGAU0013 .....VGAU0014 .....VGAU0015 .....VGAU0016 .....VGAU0017 .....VGAU0018 .....VGAU0019 .....VGAU0020 .....VGAU0021 .....VGAU0022 .....VGAU0023 .....VGAU0024 .....VGAU0025 .....VGAU0026 .....VGAU0027 .....VGAU0028 .....VGAU0029 .....VGAU0030 .....VGAU0031 .....VGAU0032 .....VGAU0033 .....VGAU0034 .....VGAU0035 .....VGAU0036 .....VGAU0037 .....VGAU0038 .....VGAU0039 .....VGAU0040 .....VGAU0041 .....VGAU0042 .....VGAU0043 .....VGAU0044 .....VGAU0045 .....VGAU0046 .....VGAU0047 .....VGAU0048 .....VGAU0049 .....VGAU0050 .....VGAU0051 .....VGAU0052 .....VGAU0053 .....VGAU0054 .....VGAU0055 .....VGAU0056 .....VGAU0057 .....DEXV0001 .....DEXV0002
C..... SUBROUTINE VGAUBN(C, NACT, IACT, PAR, V, N, IX, IA)
C..... ARGUMENTS
C..... INTEGER NACT, IACT(NACT), N, IX, IA(N)
C..... REAL X(IX,N)
C..... DOUBLE PRECISION C, PAR(NACT), V(NACT,NACT)
C..... LOCAL SCALARS
C..... INTEGER IND
C..... DOUBLE PRECISION F2C, TEMP, EITHER, ZERO, BIG
C..... FUNCTION CALLED
C..... DOUBLE PRECISION RMILLS
C..... MACHINE-DEPENDENT CONSTANT - BIG ROUGHLY CHOSEN SO THAT
C..... DEXP(X) WILL CAUSE EXCEPTION IF /X/ > BIG
C..... DATA ZERO, BIG /0.000, 174.000/
C..... SET UPPER TRIANGLE OF V(.,.) TO ZERO
C..... DO 10 J = 1, NACT
C.....   DO 10 I = J, NACT
C.....     V(I,J) = ZERO
C..... MAIN LOOP OVER SAMPLE
C..... DO 70 I = 1, N
C.....   F2C = ZERO
C.....   DO 20 J = 1, NACT
C.....     IND = IACT(J)
C.....     F2C = F2C + PAR(J) * X(IND,I)
C..... 20  CONTINUE
C.....   TEMP = C * F2C * F2C
C.....   IF (DABS(TEMP) .GE. BIG) GO TO 70
C.....   IF (IA(I) EO O) GO TO 30
C.....   EITHER = RMILLS(-F2C)
C.....   GO TO 40
C..... 30  EITHER = RMILLS(F2C)
C.....   40  F2C = DEXP(-TEMP) * EITHER * EITHER
C.....   DO 60 J = 1, NACT
C.....     IND = IACT(J)
C.....     TEMP = F2C * X(IND,I)
C.....     DO 50 K = J, NACT
C.....       IND = IACT(K)
C.....       V(K,J) = V(K,J) + TEMP * X(IND,I)
C.....     50  CONTINUE
C.....     60  CONTINUE
C.....   70  CONTINUE
C..... DIVIDE V(.,.) BY SAMPLE SIZE. FILL OUT
C..... TEMP = DBLE(FLOAT(N))
C..... DO 80 J = 1, NACT
C.....   DO 80 I = 1, NACT
C.....     V(I,J) = V(I,J) / TEMP
C.....     V(J,I) = V(I,J)
C..... 80  CONTINUE
C..... RETURN
C..... END
C..... FIRST AND SECOND PARTIAL DERIVATIVES FOR BINARY EXTREME

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C      VALUE, REGRESSION PARAMETERIZATION. PARTIALS ARE SCALED          DEXV0003
C      BY SAMPLE SIZE                                         DEXV0004
C      FAILURE CODE - IFAULT = -1 - AN EXCEPTION WOULD HAVE          DEXV0005
C      OCCURRED WHEN PROCESSING THE I TH OBSERVATION          DEXV0006
C.....SUBROUTINE DEXVBNC, OBJECT, NACT, IACT, PAR, GRAD, HESS, N, IX,
C      X, IA, IFAULT)                                         DEXV0007
C
C      ARGUMENTS                                              DEXV0008
C      INTEGER NACT, IACT(NACT), N, IX, IA(N), IFAULT           DEXV0009
C      REAL X(IX,N)
C      DOUBLE PRECISION C, OBJECT, PAR(NACT), GRAD(NACT), HESS(NACT,MACT) DEXV0010
C      LOCAL SCALARS                                         DEXV0011
C      LOGICAL MLE                                           DEXV0012
C      INTEGER IND                                           DEXV0013
C      DOUBLE PRECISION EXTRA, DOT, EXPON, DENFAC, EXPEXP, FC, EITHER, DEXV0014
C      MTERM, ZERO, ONE, BIG, BIGI, DEXV0015
C      MACHINE-DEPENDENT CONSTANTS - BIG ROUGHLY CHOSEN SO THAT DEXV0016
C      EXP(X) WILL CAUSE EXCEPTION IF |X| > BIG, BIGI SUCH DEXV0017
C      THAT 1.000 / DEXP(DEXP(X)) NE 1.000 IF |X| > BIGI DEXV0018
C      DATA ZERO, ONE, BIG, BIGI / 0.000, 1.000, 174.000, -36.2D0/ DEXV0019
C
C      IFAULT = 0                                            DEXV0020
C      MLE = ONE + C EQ ONE                                 DEXV0021
C      EXTRA = ONE / PAR(1)                                DEXV0022
C      OBJECT = ZERO                                     DEXV0023
C      DO 10 J = 1, NACT                                DEXV0024
C      GRAD(J) = ZERO                                    DEXV0025
C      DO 10 I = 1, J, MACT                            DEXV0026
C      HESS(I,J) = ZERO                                DEXV0027
C      10 CONTINUE                                         DEXV0028
C
C      MAIN LOOP OVER SAMPLE                           DEXV0029
C      DO 90 I = 1, N                                     DEXV0030
C      DOT = ZERO                                      DEXV0031
C      DO 20 J = 1, MACT                               DEXV0032
C      IND = IACT(J)                                  DEXV0033
C      DOT = DOT + PAR(J) * X(IND,1)                  DEXV0034
C
C      20 CONTINUE                                         DEXV0035
C      IF (DABS(DOT) GE BIG) GO TO 110                DEXV0036
C      IF (PAR(J) EQ BIG) GO TO 110                   DEXV0037
C      IND = IACT(J)                                  DEXV0038
C      DOT = DOT + PAR(J) * X(IND,1)                  DEXV0039
C
C      20 CONTINUE                                         DEXV0040
C      IF (DABS(DOT) GE BIG) GO TO 110                DEXV0041
C      EXPON = DEXP(DOT)                                DEXV0042
C      DENFAC = ONE - EXPON                            DEXV0043
C      IF (IA(I) EQ 0) GO TO 40                         DEXV0044
C
C      FAILURE TERM, IA(I) = 1                         DEXV0045
C      IF (EXPON GE BIG OR DOT LE BIG) GO TO 110      DEXV0046
C      EXPEXP = DEXP(EXPON)                            DEXV0047
C      DOT = ONE - ONE / EXPEXP                      DEXV0048
C      FC = EXPON / EXPEXP                            DEXV0049
C      EITHER = FC / DOT                            DEXV0050
C      MTERM = EITHER * (DENFAC - EITHER)            DEXV0051
C      IF (MLE) GO TO 30                                DEXV0052
C      FC = FC .. C                                   DEXV0053
C      GO TO 60                                       DEXV0054
C
C      30 OBJECT = OBJECT + DLOG(DOT)                 DEXV0055
C      GO TO 60                                       DEXV0056
C
C      NON FAILURE TERM, IA(I) = 0                   DEXV0057
C      EITHER = EXPON                                DEXV0058
C      MTERM = EITHER                                DEXV0059
C
C      40

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```

IF (MLE) GO TO 50
FC = C * (DOT - EXPON)
IF (DABS(FC) GE BIG) GO TO 110
FC = DEXP(FC)
GO TO 60
50   FC = ONE
      OBJECT = OBJECT + EITHER
C
C   LOOP TO INCREMENT THE DERIVATIVES
      EITHER = FC * EITHER
      MTERM = FC * MTERM
      FC = C * EITHER
      DO 80 J = 1, NACT
        IND = IACT(J)
        DOT = DBLE(X(IND,1))
        GRAD(J) = GRAD(J) + DOT * EITHER
        EXPON = DOT * DENFAC
        IF (J EQ 1) EXPON = EXPON + EXTRA
        EXPON = FC * EXPON + DOT * MTERM
        DO 70 K = J, NACT
          IND = IACT(K)
          HESS(K,J) = HESS(K,J) + X(IND,1) * EXPON
70    CONTINUE
80    CONTINUE
90    CONTINUE

C   SCALE PARTIALS BY SAMPLE SIZE. NORMAL EXIT
      EXTRA = DBLE(FLOAT(N))
      DO 100 J = 1, NACT
        GRAD(J) = GRAD(J) / EXTRA
      DO 100 I = J, NACT
        HESS(I,J) = HESS(I,J) / EXTRA
        HESS(J,I) = HESS(I,J)
100  CONTINUE
      RETURN
C   ERROR EXIT - EXCEPTIONS
      110 IF(AUT = -1)
C   RETURN
END
C*****COMPUTE VI***1 FACTOR FOR ASYMPTOTIC COVARIANCE MATRIX.
C*****BINARY EXTREME VALUE CALLED ONLY WHEN C NE O
C*****SUBROUTINE VEXVM(C, NACT, IACT, PAR, V, N, IX, IA)
C   ARGUMENTS
      INTEGER NACT, IACT(NACT), N, IX, IA(N)
      REAL X(IX,N)
      DOUBLE PRECISION C, PAR(NACT), V(NACT,NACT)
C   LOCAL SCALARS
      INTEGER IND
      DOUBLE PRECISION DOT, EXPON, FC, ZERO, BIG!
      MACHINE-DEPENDENT CONSTANTS BIG ROUGHLY CHOSEN SO THAT
      DEXP(X) WILL CAUSE EXCEPTION IF /X/ GT. BIG, BIG! SUCH
      THAT 1 000 / DEXP(DEXP(X)) NE 1 000 IF X GT. BIG!
      DATA ZERO, ONE, BIG, BIG1 /0.000, 1.000, 174.000, -36.200/
C   SET UPPER TRIANGLE OF V(*,*)
      DO 10 J = 1, NACT
        DO 10 I = 1, NACT
          V(I,J) = 0.0
        CONTINUE
      CONTINUE
      RETURN
END

```

```

DO 10 I = J, NACT
10 V(I,J) = ZERO
C
C      MAIN LOOP OVER SAMPLE
C
DO 70 J = 1, N
    DOT = ZERO
    DO 20 K = 1, NACT
        IND = IACT(J)
        DOT = DOT + PARI(J) * X(IND,1)
    20 CONTINUE
        IF (DABS(DOT) .GE. BIG) GO 10 70
        EXPON = DEXP(DOT)
        IF (IA(I)) EQ 0) GO 10 30
        IF (DOT LT BIG1) GO 10 70
        FC = DEXP(EXPON)
        DOT = ONE - ONE / FC
        FC = EXPON / FC
        EXPON = FC / DOT
        FC = EXPON * FC ** C
        GO 10 40
        FC = C * (DOT - EXPON)
        IF (DABS(FC) GT BIG) GO 10 70
        FC = EXPON * DEXP(FC)
C
C      SUMMANDS FOR V(*,*)
        FC = FC * FC
        DO 60 J = 1, NACT
            IND = IACT(J)
            DOT = FC * X(IND,1)
            DO 50 K = J, NACT
                IND = IACT(K)
                V(K,J) = V(K,J) + DOT * X(IND,1)
            50 CONTINUE
            60 CONTINUE
        70 CONTINUE
C
C      DIVIDE V(*,*) BY SAMPLE SIZE. FILL OUT
        DOT = DBLE(FLOAT(N))
        DO 80 J = 1, NACT
            DO 80 I = J, NACT
                V(I,J) = V(I,J) / DOT
                V(J,I) = V(I,J)
        80 CONTINUE
C
C      RETURN
END
C
C      DOUBLE PRECISION MATRIX MULTIPLICATION
C      X(N1 BY N3) * Y(N1 BY N2) * Z(N2 BY N3)
C
C      THREE OPTIONS -
C      IFLAG = 0 - X, Y, AND Z ARE DISTINCT
C      IFLAG LT 0 - X, Y OVERLAP, CORNER OF Y OVERWRITTEN
C      IFLAG GT 0 - X, Z OVERLAP, CORNER OF Z OVERWRITTEN
C
C
SUBROUTINE DMXMLT(X, IX, N1, Y, IY, N2, Z, IZ, N3, WORK, LWORK,
     1 IFLAG, IFAULT)
C
C      ARGUMENTS
C      INTEGER IX, N1, IY, N2, IZ, N3, LWORK, IFLAG, IFAULT
C      DOUBLE PRECISION X(IIX,N3), Y(IY,N2), Z(IZ,N3), WORK(LWORK)
C      LOCAL SCALARS

```

```

DOUBLE PRECISION TEMP, ZERO
DATA ZERO / 0.000/
C
C     ERROR EXITS
C
 1 IF(AULT = 1)
 1 IF ((MIN0(N1,N2,N3) .LT. 1 OR MIN0(IY,IY) .LT. N1 .OR. IZ .LT.
 1 N2)) RETURN
 1 IF(AULT = 2)
 1 IF (IIFLAG .LT. 0 AND (N3 GT N2 .OR. LWORK .LT. N3))
 1 RETURN
 1 IF(AULT = 3)
 1 IF (IIFLAG .GT. 0 AND (N1 GT IZ .OR. LWORK .LT. N1))
 1 RETURN
 1 IF(AULT = 0)
 1 IF (IIFLAG NE 0) GO TO 30
C
C     STRAIGHTFORWARD, NO OVERWRITING
C
 20 DO 20 I = 1, N1
 20 DO 20 J = 1, N3
 20 TEMP = ZERO
 20 DO 10 K = 1, N2
 10 TEMP = TEMP + Y(I,K) * Z(K,J)
 20 X(I,J) = TEMP
 20 CONTINUE
 20 RETURN
C
C     CORNER OF MATRIX Z IS OVERWRITTEN
C
 30 IF (IIFLAG LT 0) GO TO 80
 30 DO 70 J = 1, N3
 30 DO 50 I = 1, N1
 30 TEMP = ZERO
 30 DO 40 K = 1, N2
 40 TEMP = TEMP + Y(I,K) * Z(K,J)
 40 WORK(I) = TEMP
 50 CONTINUE
 50 DO 60 I = 1, N1
 60 X(I,J) = WORK(I)
 70 CONTINUE
 70 RETURN
C
C     CORNER OF MATRIX Y IS OVERWRITTEN
C
 80 DO 120 I = 1, N1
 80 DO 100 J = 1, N3
 80 TEMP = ZERO
 80 DO 90 K = 1, N2
 90 TEMP = TEMP + Y(I,K) * Z(K,J)
 90 WORK(J) = TEMP
 100 CONTINUE
 100 DO 110 J = 1, N3
 110 X(I,J) = WORK(J)
 120 CONTINUE
 120 RETURN
C
C     END
C
C     DOUBLE PRECISION VERSION OF ALGORITHM AS 66, APPLIED
C     STATISTICS (1973), VOL 22, NO 3
C     EVALUATES THE TAIL AREA OF THE STANDARD NORMAL CURVE
C     FROM X TO INFINITY IF UPPER IS TRUE, OR FROM
C     MINUS INFINITY TO X IF UPPER IS FALSE
C

```

```

C..... DOUBLE PRECISION FUNCTION ALNORM(X,UPPER)
C      ARGUMENTS
C      LOGICAL UPPER
C      DOUBLE PRECISION X
C      LOCAL SCALARS
C
C      LOGICAL UP
C
C      DOUBLE PRECISION LTONE, UTZERO, ZERO, HALF, ONE, CON, Z, Y
C
C      MACHINE-DEPENDENT CONSTANTS - LTONE = (N + 9) / 3, WHERE
C      N IS NO. OF DECIMAL DIGITS IN DOUBLE PRECISION NUMBER.
C      UTZERO SUCH THAT DEXP(-X*X/2.0DO) WILL CAUSE AN EXCEPTION
C
C      IF X .GT. UTZERO
C
C      CONSTANTS IN EXPRESSIONS ARE AS IN AS 66.
C
C      DATA LTONE, UTZERO, ZERO, HALF, ONE, CON /8.000, 18.65DO, 0.0DO,
C      , 0.5DO, 1.000, 1.28DO/
C
C      UP = UPPER
C      Z = X
C      IF (Z .GE. ZERO) GO TO 10
C      UP = NOT UP
C      Z = -Z
C      10 IF (Z .LE. LTONE .OR. UP .AND. Z .LE. UTZERO) GO TO 20
C
C      ALNORM = ZERO
C      GO TO 40
C
C      20 Y = HALF * Z * Z
C      IF (Z .GT. CON) GO TO 30
C
C      ALNORM = HALF - Z * (0.3989422804440D-0 - 3.99903438504D0*Y/(Y + 5.
C      175885480458D-29 8213557808D0/(Y + 2.62433121679D+48.
C      26959930692D0/(Y + 5.92885724438D0))),)
C      GO TO 40
C
C      30 ALNORM = 0.398942280385D0 + DEXP(-Y) / ((Z - 3.8052D-8 + 1.
C      100000615302D0/(Z + 3.98064794D-4 + 1.98615381364D0/(Z - 0.
C      2151679116635D0+5.2930324926D0/(Z + 4.8385912808D0-15.
C      31508972451D0/(Z + 0.742380924027D0+30.789933034D0/(Z + 3.
C      499019417011D0))))))
C
C      40 IF ( .NOT. UP) ALNORM = ONE - ALNORM
C
C      RETURN
C      END
C
C      LOGICAL UP
C
C      RECIPROCAL OF MILLS RATIO, Z(X) / O(X), X A STANDARD NORMAL
C      VARIATE. BASED ON FUNCTION ALNORM(). ALGORITHM AS 66.
C
C      DOUBLE PRECISION FUNCTION RMILLS(X)
C
C      ARGUMENTS
C      DOUBLE PRECISION X
C      LOCAL SCALARS
C
C      LOGICAL UP
C
C      DOUBLE PRECISION Z, Y, LTONE, UTZERO, ZERO, HALF, ONE, CON, FP11,
C      , FP12
C
C      MACHINE-DEPENDENT CONSTANTS - LTONE = (N + 9) / 3, WHERE
C      N IS NO. OF DECIMAL DIGITS IN DOUBLE PRECISION NUMBER.
C      UTZERO SUCH THAT DEXP(-X*X/2.0DO) WILL CAUSE AN EXCEPTION
C
C      IF X .LT. UTZERO
C
C      FP11 = SQRT(2/PI)
C      FP12 = 1/SQRT(2*PI)
C
C      CONSTANTS IN EXPRESSIONS ARE AS IN AS 66.
C
C      DATA LTONE, UTZERO, ZERO, HALF, ONE, CON, FP11, FP12 /8.0DO,

```

```

1      -18 65DO, 0 0DO, 0 5DO, 1 0DO, 1 28DO, 7 9788456080286536D-1, RMIL0019
2      3 9894228040143268D-1/
C
C   TRIVIAL CASES
C     IF (X NE. ZERO) GO TO 10
C     RMILLS = FP11
C     RETURN
10    IF (X GT. UTZERO) GO 10 20
C     RMILLS = ZERO
C     RETURN
C
C   USUAL SITUATION
C     20 UP = TRUE.
C     Z = X
C     IF (Z GE. ZERO) GO 10 30
C     UP = FALSE.
C     Z = -Z
30    Y = HALF * Z * Z
C     IF (Z GT. CONJ) GO TO 50
C
C   CENTRAL PORTION - O LT ABS(X) LT 1.28
C   RMILLS = Z * (0.39894228044400-0 399903438504DO*Y/(Y + 5
1/5885480458DO-29 8213557808DO/(Y + 2.62433121679DO+48
26959930692DO/(Y + 5 92885724438DO))) )
C   Y = FP12 * DEXP(-Y)
C   IF (UP) GO TO 40
C   RMILLS = Y / (HALF + RMILLS)
C   RETURN
40    RMILLS = Y / (HALF - RMILLS)
C   RETURN
C
C   OUTER PORTION - ABS(X) GE 1.28
50    IF (UP OR Z LE. LTONE) GO 10 60
C
C   SPECIAL CASE - LOWER TAIL AND Q ESSENTIALLY 1
C   RMILLS = FP12 * DEXP(-Y)
C   RETURN
C
C   USUAL SITUATION
60    RMILLS = (Z - 3 8052D 8 + 1 00000615302DO/(Z + 3.98064794D-4 + 1. RMIL0058
198615381364DO/(Z - 0 151679116635DO+5.29330324926DO/(Z + 4. RMIL0059
28385912808DO 15.1508972451DO/(Z + 0.742380924027DO+30.789933034DO/RMIL0060
312 + 3 990194170110D)))) )
C
C   IF (UP) RETURN
C   Y = FP12 * DEXP(-Y)
C   RMILLS = Y / (ONE - Y/RMILLS)
C
C   RETURN
END

```

```

      SAMPLE MAIN PROGRAM AND INPUT SUBROUTINE FOR SELF-CRITICAL
      BINARY ESTIMATION. IT IS RECOMMENDED THAT BINARY() AND
      ITS AUXILIARY PROCEDURES BE COMPILED AND PLACED IN AN
      OBJECT CODE LIBRARY, SO THE USER CAN CALL BINARY() FROM
      ARBITRARY PROGRAMS.

      INTEGER N, IX, IA(750), INPAR, ISUB(10), ISTART(10), IDEP,
      MAXIT, IPRINT, IFLAG, ICOV, LMEM, MEMORY(490), IFAULT, NC,
      NMMAX, NCMAX, IREAD
      REAL X(10,750)
      DOUBLE PRECISION C(5), RELTOL, ABSTOL, BETA(10), XLOGL, COV(10,10)
      DATA IX, INPAR, LMEM, NMMAX / 10, 490, 750, 5 /
      DATA MAXIT, RELTOL, ABSTOL, IPRINT, ICOV / 15, 1.0D-7, 1.0D-7, 6 /
      DATA O/
      DATA IREAD /5/
      C
      C   DIMENSION SPECIFICATIONS FOR ARRAYS.
      C   THIS MAIN PROGRAM CAN HANDLE UP TO 750 OBSERVATIONS.
      C   WITH UP TO 10 PARAMETERS AND 5 DIFFERENT VALUES OF
      C   C FOR ESTIMATION.
      C   DATA IX, INPAR, LMEM, NMMAX / 10, 490, 750, 5 /
      C
      C   BASIC INFORMATION TO PASS TO BINARY() - IPRINT STANDS
      C   FOR LOGICAL OUTPUT UNIT 6
      C   DATA MAXIT, RELTOL, ABSTOL, IPRINT, ICOV / 15, 1.0D-7, 1.0D-7, 6 /
      C   DATA O/
      C
      C   IREAD IS LOGICAL INPUT UNIT 5
      C   DATA IREAD /5/
      C
      C   SPECIFY EVERYTHING BY HAND IN SUBROUTINE INPUT - ARRAY
      C   MEMORY(*) PASSED AS WORKSPACE
      C   CALL INPUT(IX, N, NMMAX, X, TA, NPAR, BETA, ISUB, ISTART, NC,
      C   , NMMAX, C, IDEP, IDIST, IREAD, IPRINT, IFLAG, IFAULT)
      C   IF (IAUTH .EQ. 0) GO TO 10
      C   IF (IAUTH .EQ. 1) WRITE (IPRINT, 50) N, NMMAX
      C   IF (IAUTH .EQ. 2) WRITE (IPRINT, 60) NPAR, IX
      C   IF (IAUTH .EQ. 3) WRITE (IPRINT, 70) NC, NCMAX
      C   WRITE (IPRINT, 80)
      STOP
      C
      C   LOOP OVER THE VALUES OF C REQUESTED FOR ESTIMATION
      10 DO 40 I = 1, NC
      CALL BINARY(IN, IX, X, TA, NPAR, ISUB, ISTART, IDEP, IDIST, C(1),
      1 RELTOL, ABSTOL, MAXIT, IPRINT, IFLAG, BETA, XLOGL, ICOV,
      2 COV, LMEM, MEMORY, IFAULT)
      1 IF (IAUTH .EQ. 0) GO TO 20
      2 WRITE (IPRINT, 90) IFAULT
      STOP
      20 IF (I .GT. 1) GO TO 40
      C
      C   AFTER THE FIRST ESTIMATION, SET ISTART(*) TO 1, SO
      C   LATEST ESTIMATES CAN BE USED AS STARTING VALUES
      C   DO 30 J = 1, NPAR
      30 ISTAR1(J) = 1
      C   40 CONTINUE
      C
      50 FORMAT ('ERROR - SAMPLE SIZE OF ', 110, ' EXCEEDS DIMENSION OF '.
      1 ' 10)
      60 FORMAT ('PARAMETERS EXCEEDS DIMENSION OF ', 13)
      70 FORMAT ('C VALUES EXCEEDS DIMENSION OF ', 13)
      80 FORMAT ('RECOMPILE MAIN PROGRAM WITH NEW DIMENSIONS ')
      C
      C   MAIN0002
      C   MAIN0003
      C   MAIN0004
      C   MAIN0005
      C   MAIN0006
      C   MAIN0007
      C   MAIN0008
      C   MAIN0009
      C   MAIN0010
      C   MAIN0011
      C   MAIN0012
      C   MAIN0013
      C   MAIN0014
      C   MAIN0015
      C   MAIN0016
      C   MAIN0017
      C   MAIN0018
      C   MAIN0019
      C   MAIN0020
      C   MAIN0021
      C   MAIN0022
      C   MAIN0023
      C   MAIN0024
      C   MAIN0025
      C   MAIN0026
      C   MAIN0027
      C   MAIN0028
      C   MAIN0029
      C   MAIN0030
      C   MAIN0031
      C   MAIN0032
      C   MAIN0033
      C   MAIN0034
      C   MAIN0035
      C   MAIN0036
      C   MAIN0037
      C   MAIN0038
      C   MAIN0039
      C   MAIN0040
      C   MAIN0041
      C   MAIN0042
      C   MAIN0043
      C   MAIN0044
      C   MAIN0045
      C   MAIN0046
      C   MAIN0047
      C   MAIN0048
      C   MAIN0049
      C   MAIN0050
      C   MAIN0051
      C   MAIN0052
      C   MAIN0053
      C   MAIN0054
      C   MAIN0055
      C   MAIN0056
      C   MAIN0057
      C   MAIN0058
      C   MAIN0059
      C   MAIN0060

```

```

90 FORMAT ('ESTIMATION PROCEDURE HAS FAILED - IFAULT = ', I6)
      STOP
      END

C***** CRUDE INPUT ROUTINE SETS ESTIMATION CONTROL PARAMETERS
C***** EXPLICITLY. INSTEAD OF READING THEM IN
C***** SUBROUTINE INPUT (IX, N, NMAX, X, IA, NPAR, BETA, ISUB, ISTART,
C***** NCMAX, C, IDEP, IDIST, WORK, IREAD, IPRINT, IFAULT)
      1   ARGUMENTS
      INTEGER IX, N, NMAX, IA(1), NPAR, ISUB(1), ISTART(1), NC, NCMAX,
      , IDEP, IDIST, IPRINT, IFAULT
      REAL X(IX,1), WORK(1)
      DOUBLE PRECISION BETA(1), C(1)

C LOCAL TYPE DECLARATION
C LOGICAL FLAG

C SET DETAILS OF PROBLEM SIZE
      N = 680
      NPAR = 5
      NC = 4

C CHECK FOR SIZE ERRORS
      IFAULT = 1
      IF (N GT NMAX) RETURN
      IFAULT = 2
      IF (NPAR GT 1X) RETURN
      IFAULT = 3
      IF (NC GT NCMAX) RETURN
      IFAULT = 0

C MODELING DETAILS
C DEPENDENT VARIABLE IN FIRST ROW
      IDEP = 1
      CONSTANT IN SECOND ROW
     ICONST = 2
      GAUSSIAN TOLERANCE DISTRIBUTION
      IDIST = 2
      VALUES OF C FOR SELF-CRITICAL
      C(1) = 0.000
      C(2) = 0.100
      C(3) = 0.200
      C(4) = 0.300

C INITIALIZE AVERAGES TO 0
      YBAR = 0.0
      YSE = 0.0
      DO 10 I = 1, NPAR
      10 WORK(I) = 0.0

C LOOP OVER SAMPLE TO READ IN DATA
      FLAG = NPAR .LE. 2
      DO 40 I = 1, N
      READ (IREAD,20) VC, IA(1), ALPHA, S
      20  FORMAT (F10.0, 12. 2FB0)
      C EXPRESS S IN METERS, SCALE VC
      VC = ALOG(VC/1000.0)
      S = 0.3048 * EXP(S)

      40  INPUT001
          INPUT002
          INPUT003
          INPUT004
          INPUT005
          INPUT006
          INPUT007
          INPUT008
          INPUT009
          INPUT010
          INPUT011
          INPUT012
          INPUT013
          INPUT014
          INPUT015
          INPUT016
          INPUT017
          INPUT018
          INPUT019
          INPUT020
          INPUT021
          INPUT022
          INPUT023
          INPUT024
          INPUT025
          INPUT026
          INPUT027
          INPUT028
          INPUT029
          INPUT030
          INPUT031
          INPUT032
          INPUT033
          INPUT034
          INPUT035
          INPUT036
          INPUT037
          INPUT038
          INPUT039
          INPUT040
          INPUT041
          INPUT042
          INPUT043
          INPUT044
          INPUT045
          INPUT046
          INPUT047
          INPUT048
          INPUT049
          INPUT050
          INPUT051
          INPUT052
          INPUT053
          INPUT054
          INPUT055
          INPUT056
          INPUT057

```

```

C FILL THE DATA MATRIX - CONSTANT IN SECOND ROW
      X(1DEP,1) = VC
      X(1CONST,1) = 1.0
      X(3,1) = ALPHA
      X(4,1) = S
      X(5,1) = ALPHA * S

C UPDATE MEAN AND STD ERROR OF DEPENDENT VARIABLE IN A
C MAY WHICH DOESN'T LOSE SIGNIFICANT FIGURES
      TEMP = VC - YBAR
      YBAR = YBAR + TEMP / FLOAT(I)
      YSE = YSE + TEMP * (VC - YBAR)

C INCREMENT COVARIATE AVERAGES (3D ROW AND UP)
      IF (FLAG) GO TO 40
      DO 30 J = 3, NPAR
         WORK(J) = WORK(J) + X(J,1)

30   CONTINUE

C 40 CONTINUE

C SET ISUB(*) AND ISTART(*) . PROVIDING STARTING VALUES
C FOR INTERCEPT AND SCALE
      DO 50 I = 1, NPAR
         ISUB(I) = 1
         ISTART(I) = 0
50   CONTINUE
      TEMP = FLOAT(N)
      YSE = SORT(YSE/TEMP)
      ISTART(1DEP) = 1
      BETA(1DEP) = DBLE(YSE)
      ISTART(ICONST) = 1
      BETA(ICONST) = DBLE(YBAR)

C WRITE OUT INFORMATION ON STD. ERROR AND AVERAGES
      WRITE (IPRINT,60) YBAR, YSE
60   FORMAT ('1DEPENDENT (STRESS) VARIABLE', '/ ONEAN = ', E14.6,
     , ' STANDARD DEVIATION = ', E14.6)
      IF (FLAG) RETURN
      WRITE (IPRINT,70)
70   FORMAT ('OCOVARIATES HAVE BEEN CENTERED BY THEIR MEANS',
     , 'OVARIALE', '10X, 'MEAN')
      DO 90 I = 3, NPAR
         WORK(I) = WORK(I) / TEMP
         WRITE (IPRINT,80) ISUB(I), WORK(I)
90   FORMAT ('O', '18. E14.6)
      CONTINUE

C SUBTRACT MEANS FROM COVARIATES
      DO 110 I = 1, N
        DO 100 J = 3, NPAR
          X(J,1) = X(J,1) - WORK(J)
100   CONTINUE
110 CONTINUE

C RETURN
END

```

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